

Ref. R V 50 UO3D/25 V5 Technical Report 1.0

2013.02 n. 741073

Standard product : Yes

DE-17-000744/00 pos. 1 Worm Gear reducer - catalogue A04

Application given data N.A.

Designation: R V 50 UO3D/25 V5 Mounting position V5, $n_1 = 2800$ [min⁻¹]

Nounting position v_3 , $n_1 = 2000$

Accessories and special designs

Viton seal rings on high speed shaft (TV1)

Reducer/Gearmotor specifications Transmission ratio i Output speed n_2 Input speed n_1 Input power P_1 Output torque M_2 Service factor fs Efficiency Mass of gear reducer (without motor) Previsional lubricant quantity ISO viscosity grade	[min ⁻¹] [min ⁻¹] [kW] [N m] [kg] [1] [cSt]	25 112 2800 N.A. N.A. N.A. 0,82 9 0,4 320
Nominal Data Nominal input power P_{N1} Nominal output power P_{N2} Nominal output torque M_{N2} Maximum output torque M_{2max}	[kW] [kW] [N m] [N m]	1,43 1,17 100 175
Verifications Safety factor on M _{2peak} Thermal power verfication External loads verificaton		N.A. N.A. N.A.

Top view with M.P. B3



The results of calculations in this document have no validity in terms of warranty. Computing: a) are theoretical, b) are based on the assumptions for optimal working conditions specified on Rossi catalogues, c) they rely on the truthfulness of given input data for which the customer is the only responsible, d) any omitted data or not taken into account by the customer voids the entire report. All contents, and information in this document are sole property of Rossi S.p.A. It cannot be disclosed for purposes other than the scope for which it has been generated under the agreement between the Customer and an authorized Rossi representative. It cannot be reproduced (in whole or in part) without explicit written permission by Rossi S.p.A. legal representative, and in this case the intellectual property of the document remains solely of Rossi S.p.A.



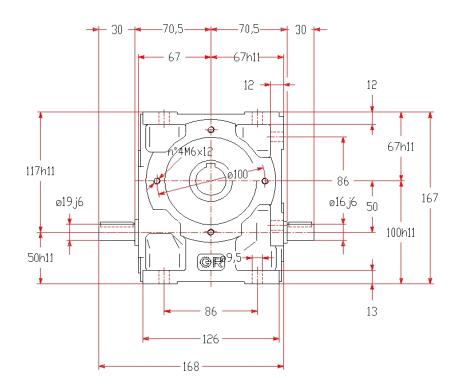
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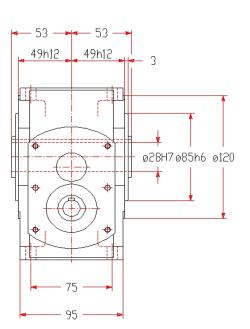
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Main Dimensions [mm] (only for standard gearbox, in case of non-standard design see the drawing on the next page)





Informations and warnings:

Worm gear pair Z2/Z1 = 25/1; Axial module = 3; Helix angle = $6^{\circ}58'$; Static efficiency = 0,48; Uncertain static reversibility; Dynamic reversibility, after running-in, with efficiency > 0,6.

Fastening nuts: M8 UNI 5588. With screw UNI 5737, see pag. 81 Cat. A04 rev.11-06/2

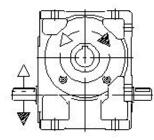
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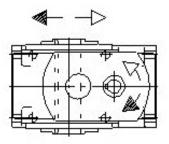
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Design: UO3D

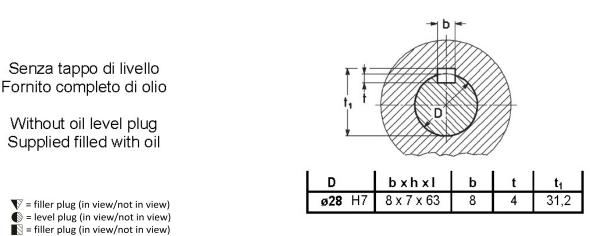


Plugs position

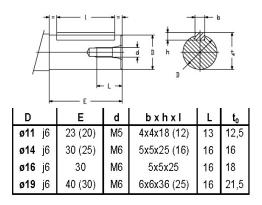
Mounting position: V5



Standard hollow low speed shaft



High speed shaft: ø19j6



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