## Application

The JOVENTA STANDARD electric damper actuator series is designed to operate air dampers in ventilation and air conditioning systems. The compact design and universal adapter fitted with limitation of rotation angle make this JOVENTA actuator highly versatile.

## Features

- $\mathrm{DC} 0(2) \ldots 10 \mathrm{~V}$ or $0(4) \ldots 20 \mathrm{~mA}$ control signal
- Working area adjustable
- Load-independent running time
- Up to 5 actuators in parallel operation possible
- Plug-in terminal block connection
- Simple direct-mount with univer-sal adapter on $10 \ldots 20 \mathrm{~mm} \varnothing$ round-axis or $10 . . .16 \mathrm{~mm}$ square shaft 48 mm minimum damper shaft lenght
- Selectable direction of rotation
- Limitation of rotation angle
- Manual release button
- 2 adjustable auxiliary switches
- Automatic shut-off at end position (overload switch)
- Actuators available with 1 m cable
- Customized versions available
- Devices meet CE requirements


## Accessories

- ZK Damper linkage selection
- ZKG Ball joints

Ordering Codes

| Codes | Descriptions |
| :--- | :--- |
| DMx1.1 | AC/DC 24 V |
| DM×1.1S | AC/DC 24 V , with 2 auxiliary switches |



Technical Specifications

| Actuator | DMS1.1(S) | DM1.1(S) | DML1.1(S) |
| :---: | :---: | :---: | :---: |
| Torque | 8 Nm | 16 Nm | 24 Nm |
| Damper area* | $1.5 \mathrm{~m}^{2}$ | 3.0 m ${ }^{2}$ | $4.5 \mathrm{~m}^{2}$ |
| Running Time OPEN | 30 s | 80 s | 125 s |
| Running Time CLOSE | 30 s | 80 s | 125 s |
| Supply Voltage | AC/DC 24 V |  |  |
| Frequency | $50-60 \mathrm{~Hz}$ |  |  |
| Power Consumption <br> - Running <br> - At end position | $\begin{aligned} & 2.5 \mathrm{~W} \\ & 0.3 \mathrm{~W} \end{aligned}$ |  |  |
| Dimensioning | 6.0 VA / 3.6 A @ 2 ms |  |  |
| Working area Y | not adjustable |  |  |
| Control Signal Y1 | DC 0... 10 V |  |  |
| Imput resistance Y1 | Ri $250 \Omega$ |  |  |
| Control signal Y2 | 0... 20 mA |  |  |
| Imput resistance Y2 | Ri 388 ת |  |  |
| Position signal U | DC $0 . . .10 \mathrm{~V}$ |  |  |
| Load resistance | $>50 \mathrm{k} \Omega$ |  |  |
| Angle of rotation/ Working range | $90^{\circ}$ (93 ${ }^{\circ} \mathrm{mech}$.) |  |  |
| Angle of rotation/ Limitation | $5^{\circ} \ldots 85^{\circ}$ in $5^{\circ}$ < steps |  |  |
| Auxiliary Switches <br> - S1 setting range <br> - S2 setting range | $5^{\circ} \ldots . .85^{\circ}$ < adjustable |  |  |
| Cable <br> - Motor <br> - Switches | 1.0 m halogen-free 5-Wire 1-2-4-5-6 5-Wire 21-22-23-24-25 |  |  |
| Life time | 60.000 rotations |  |  |
| Noise level | $45 \mathrm{~dB}(\mathrm{~A})$ |  |  |
| Protection Class | 11 |  |  |
| Degree of Protection | IP 54 |  |  |
| Mode of Action | Type 1 |  |  |
| Ambient conditions <br> - Operating temperature | $-20 . .+50^{\circ} \mathrm{C} /$ IEC 721-3-3 |  |  |
| - Storage temperature | $-30 \ldots+60^{\circ} \mathrm{C} /$ IEC 721-3-2 |  |  |
| - Humidity | $5 . .95 \%$ r.F. no condensed |  |  |
| Weight | 1.1 Kg |  |  |
| Service | Maintenance-free |  |  |
| Standards <br> - Mechanics <br> - Electronics <br> - EMC Emissions <br> - EMC Immunity | EN | 29 / EN 607 N 60 730-2-14 1:92 / IEC 6 2:95 / IEC 6 | 3:96 |

*Caution: Please note damper manufacturer's information concerning the open/close torque.

## Wiring Diagram



Parallel Connections


## Position transmitter



The DMxx can also be controlled using the JOVENTA Positioner (PA/PF) with control signal of DC 0... 10 V .
For further information concerning the PA and PF positioner please refer to sheet 6.20 .

Caution: A maximum of 5 actuators can be controlled in parallel operation.

## Dimensions in mm



## Setting the control Signal



## Setting Span and OFFSET

## The potentiometers O and S help to match control signals Y 1 and Y 2

 to any make of controller.Example 1
Control signal Y1 working between DC 2... 10 V

| Setting: | Starting point | $\mathrm{O}=2$ | Setting: | Starting point |
| :--- | :--- | :--- | :--- | :--- |$\quad \mathrm{O}=3$

Start point 0

|  | Scale O | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | for Y1 (VDC) | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|  | for Y2 (mA) | 0 | 2 | 4 | 6 | 8 | 10 | 12 | 14 | 16 |

Working range S

|  | Scale S | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | for Y1 (VDC) | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|  | for Y2 (mA) | 4 | 6 | 8 | 10 | 12 | 14 | 16 | 18 | 20 |

Auxiliary Switches (S)


Override Control


The actuator DMxx can be forced to override control when wired in accordance with the diagram.

Switch position:
$1=$ Actuator runs at 10 V
$2=$ Actuator runs at $0(2) \mathrm{V}$
$3=$ Automatic control

Settings the auxiliary switches

Factory setting
Switch a at $10^{\circ}$
Switch b at $80^{\circ}$
The switching position can be manually changed to any required position by turning the ratchet.



The limitation or rotation angle can be set in $5^{\circ}$ steps by moving the adapter.


The adapter can be remove simply by pressing the adapter clip on the underside of the actuator

